Mathematical Notation
Math 122 - Calculus & Analytic Geometry II

Name: ____________________________

Use Word or WordPerfect to recreate the following documents. Each article is worth 10 points and can be printed and given to the instructor or emailed to the instructor at james@richland.edu. If you use Microsoft Works to create the documents, then you must print it out and give it to the instructor as he can’t open those files.

Type your name at the top of each document.

Include the title as part of what you type. The lines around the title aren't that important, but if you will type ---- at the beginning of a line and hit enter, both Word and WordPerfect will draw a line across the page for you.

For expressions or equations, you should use the equation editor in Word or WordPerfect. The documents were created using a 14 pt Times New Roman font with standard 1” margins.

For individual symbols (μ, σ, etc), you can insert symbols. In Word, use “Insert / Symbol” and choose the Symbol font. For WordPerfect, use Ctrl-W and choose the Greek set. For more complex expressions you should use the equation editor. If there is an equation, put both sides of the equation into the same equation editor box.

There are instructions on how to use the equation editor in a separate document. Be sure to read through the help it provides. There are some examples at the end that walk students through the more difficult problems. You will want to read the handout on using the equation editor if you have not used this software before.

If you fail to type your name on the page, you will lose 1 point.

These notations are due at the beginning of class on the day of the exam for that unit. That is, the unit 1 notation is due on the day of the unit 1 test. Late work will be accepted but will lose 10% per class period.
Chapter 7 - Inverse Functions

\[
\frac{d}{dx}[f^{-1}(x)] = \frac{1}{f'[f^{-1}(x)]} \quad \frac{dy}{dx} = \frac{1}{\frac{dx}{dy}}
\]

\[e = \lim_{x \to \infty} \left(1 + \frac{1}{x}\right)^x = \lim_{x \to 0} (1 + x)^{1/x}\]

\[
\frac{d}{dx}[e^x] = e^x \quad \frac{d}{dx}[a^x] = a^x \cdot \ln a \quad \frac{d}{dx}[\ln x] = \frac{1}{x} \quad \frac{d}{dx}[\log_a x] = \frac{1}{x \cdot \ln a}
\]

\[
\frac{d}{dx}[\sin^{-1} x] = \frac{1}{\sqrt{1-x^2}} \quad \frac{d}{dx}[\cos^{-1} x] = \frac{-1}{\sqrt{1-x^2}}
\]

\[
\frac{d}{dx}[\tan^{-1} x] = \frac{1}{1+x^2} \quad \frac{d}{dx}[\cot^{-1} x] = \frac{-1}{1+x^2}
\]

\[
\frac{d}{dx}[\sec^{-1} x] = \frac{1}{|x|\sqrt{x^2-1}} \quad \frac{d}{dx}[\csc^{-1} x] = \frac{-1}{|x|\sqrt{x^2-1}}
\]

If \(f\) and \(g\) are differentiable and \(\lim_{x \to a} f(x)\) and \(\lim_{x \to a} g(x)\) are both 0 or \(\infty\), then

\[
\lim_{x \to a} \left(\frac{f(x)}{g(x)}\right) = \lim_{x \to a} \left(\frac{f'(x)}{g'(x)}\right)
\]

\[
\frac{d}{dx}[\sinh x] = \cosh x \quad \frac{d}{dx}[\cosh x] = \sinh x
\]

\[
\frac{d}{dx}[\tanh x] = \text{sech}^2 x \quad \frac{d}{dx}[\coth x] = -\text{csch}^2 x
\]

\[
\frac{d}{dx}[\text{sech} x] = -\text{sech} x \tanh x \quad \frac{d}{dx}[\text{csch} x] = -\text{csch} x \coth x
\]
# Chapter 8 - Techniques of Integration

## Integration by Parts
\[
\int u \, dv = uv - \int v \, du
\]

## Reduction Formulas
\[
\begin{align*}
\int \sin^n x \, dx &= -\frac{1}{n} \sin^{n-1} x \cos x + \frac{n-1}{n} \int \sin^{n-2} x \, dx \\
\int \cos^n x \, dx &= \frac{1}{n} \cos^{n-1} x \sin x + \frac{n-1}{n} \int \cos^{n-2} x \, dx \\
\int \tan^n x \, dx &= \frac{1}{n-1} \tan^{n-1} x - \int \tan^{n-2} x \, dx \\
\int \sec^n x \, dx &= \frac{1}{n-1} \sec^{n-2} x \tan x + \frac{n-2}{n-1} \int \sec^{n-2} x \, dx
\end{align*}
\]

## Trigonometric Substitution
- For \( \sqrt{a^2 - x^2} \), use \( x = a \sin \theta \)
- For \( \sqrt{a^2 + x^2} \), use \( x = a \tan \theta \)
- For \( \sqrt{x^2 - a^2} \), use \( x = a \sec \theta \)

## Special Trigonometric Substitution
\[
\begin{align*}
\sin x &= \frac{2u}{1 + u^2} & \cos x &= \frac{1 - u^2}{1 + u^2} & dx &= \frac{2}{1 + u^2} \, du
\end{align*}
\]

## Errors with Numerical Integration
\[
\begin{align*}
|E_M| &\leq \frac{(b-a)^3 K_2}{24n^2} & |E_T| &\leq \frac{(b-a)^3 K_2}{12n^2} & |E_S| &\leq \frac{(b-a)^5 K_4}{180n^4}
\end{align*}
\]
Chapter 9 - Differential Equations

First order, linear differential equations can be written in the form
\[ \frac{dy}{dx} + p(x)y = q(x) \text{ or } y' + p(x)y = q(x). \]

The integrating factor for a first-order, linear differential equation is \( \mu = e^{\int p(x)dx} \).

After finding the integrating factor, multiply both sides of the equation by it to get
\[ \mu y' + \mu p(x)y = \mu q(x). \]

The left side of the equation is the derivative of a product and so the equation can be written as
\[ \frac{d}{dx} \left[ \mu y \right] = \mu q(x). \]

This equation is separable and can then be integrated to find the solution.

Models where the rate of growth (decay) is proportional to the amount present can be written as
\[ \frac{dy}{dt} = ky \] and give the model \( y = Ce^{kt} \).

Models where the rate of growth is proportional to the amount present and the amount not present can be written as
\[ \frac{dy}{dt} = ky(L - y) \] and give the model
\[ y = \frac{L}{1 + Ce^{-kt}}. \]

The solution to a second order, homogenous linear differential equation \( y'' + py' + q = 0 \) can be found by finding the roots \( m_1 \) and \( m_2 \) to the equation \( m^2 + pm + q = 0 \) and then using the form \( y(x) = c_1e^{m_1x} + c_2e^{m_2x} \), \( y(x) = c_1e^{mx} + c_2xe^{mx} \), or \( y(x) = e^{ax}(c_1 \cos bx + c_2 \sin bx) \).
Chapter 10 - Infinite Series

Maclaurin polynomial
\[ p_n(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \frac{f'''(0)}{3!}x^3 + \cdots + \frac{f^{(n)}(0)}{n!}x^n \]
\[ p_n(x) = \sum_{k=0}^{n} \frac{f^{(k)}(0)}{k!}x^k \]

Taylor Polynomial about \( x = a \)
\[ p_n(x) = \sum_{k=0}^{n} \frac{f^{(k)}(a)}{k!}(x-a)^k \]

\( \{ a_n \} \) is increasing if \( a_{n+1} - a_n \geq 0, \frac{a_{n+1}}{a_n} \geq 1 \), or \( f'(x) \geq 0 \) and decreasing if \( a_{n+1} - a_n \leq 0, \frac{a_{n+1}}{a_n} \leq 1 \), or \( f'(x) \leq 0 \).

The sum of an infinite geometric series is \( \sum_{k=0}^{\infty} ar^k = \frac{a}{1-r}, \ |r|<1 \)

Every power series will either converge at a point, converge for all real numbers, or converge on a finite open interval.

Common Maclaurin series
\[ e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots \]
\[ \cos x = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k}}{(2k)!} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \cdots \]
\[ (1 + x)^m = 1 + \sum_{k=1}^{\infty} \frac{m(m-1)\cdots(m-k+1)}{k!} x^k \]
Chapter 11 - Analytic Geometry

\[ x = r \cos \theta \quad y = r \sin \theta \quad r^2 = x^2 + y^2 \quad \tan \theta = \frac{y}{x} \]

\[ \frac{dy}{dx} = \frac{dy/d\theta}{dx/d\theta} = \frac{r \cos \theta + \sin \theta \frac{dr}{d\theta}}{-r \sin \theta + \cos \theta \frac{dr}{d\theta}} \]

\[ L = \int_{\alpha}^{\beta} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} \, d\theta \quad A = \int_{\alpha}^{\beta} \frac{1}{2} r^2 \, d\theta \]

### Standard Forms for Conic Sections

<table>
<thead>
<tr>
<th>Conic</th>
<th>Horizontal</th>
<th>Vertical</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parabola</td>
<td>[ y^2 = 4px ]</td>
<td>[ x^2 = 4py ]</td>
</tr>
<tr>
<td>Ellipse</td>
<td>[ \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1 ]</td>
<td>[ \frac{y^2}{a^2} + \frac{x^2}{b^2} = 1 ]</td>
</tr>
<tr>
<td>Hyperbola</td>
<td>[ \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1 ]</td>
<td>[ \frac{y^2}{a^2} - \frac{x^2}{b^2} = 1 ]</td>
</tr>
</tbody>
</table>

### Eliminating the xy-term

Choose an angle \( \theta \) such that \( \cot 2\theta = \frac{A - C}{B} \), \( 0^\circ < 2\theta < 180^\circ \)

### Polar Equation of Conics

#### Relation of Directrix to Pole

<table>
<thead>
<tr>
<th>Right</th>
<th>Left</th>
<th>Above</th>
<th>Below</th>
</tr>
</thead>
<tbody>
<tr>
<td>[ r = \frac{ed}{1 + e \cos \theta} ]</td>
<td>[ r = \frac{ed}{1 - e \cos \theta} ]</td>
<td>[ r = \frac{ed}{1 + e \sin \theta} ]</td>
<td>[ r = \frac{ed}{1 - e \sin \theta} ]</td>
</tr>
</tbody>
</table>

\( e = \) eccentricity (Ellipse if \( 0 < e < 1 \), Parabola if \( e = 1 \), Hyperbola if \( e > 1 \))

\( d = \) distance from pole to directrix.